Fractional Fourier Transform to Stability Analysis of Fractional Differential Equations with Prabhakar Derivatives

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Abstract. In this paper, the authors introduce the Prabhakar derivative associated with the generalised Mittag-Leffler function. Some properties of the Prabhakar integrals, Prabhakar derivatives and some of their extensions, like fractional Fourier transform of Prabhakar integrals and fractional Fourier transform of Prabhakar derivatives are introduced. This note aims to study the Mittag-Leffler-Hyers-Ulam stability of the linear and nonlinear fractional differential equations with the Prabhakar derivative. Furthermore, we give a brief definition of the Mittag-Leffler-Hyers-Ulam problem and a method for solving fractional differential equations using the fractional Fourier transform. We show that the fractional differential equations are Mittag-Leffler-Hyers-Ulam stable in the sense of Prabhakar derivatives.

Key Words and Phrases: fractional differential equation (FDE), Prabhakar fractional integral, Prabhakar fractional derivative, Mittag-Leffler function (MLF), fractional Fourier transform (FrFT), Hyers-Ulam stability (HUS).

2010 Mathematics Subject Classifications: 34A08, 42A38, 33E12

1. Introduction

Fractional calculus is a generalisation of ordinary calculus to non-integer differentiation and integration. There have been a lot of contributions to the theory of fractional calculus by famous mathematicians, such as Laplace, Fourier, Abel, Leoville Letnikov, Heaviside, Weyl, Erdelyi, Go Renfio, Mainardi et al. FDEs have recently become a very strong tool in many fields, such as physics, thermodynamics, electrical circuit theory and seepage flow in porous media, etc. The mathematicians [1, 2, 3, 4, 5] discussed FDEs and their applications up to date

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in their books. Also, there are many applications of fractional order models in bio-mathematics and engineering. In [6, 7], the wavelet method was applied for solving fractional order model of COVID-19. The fractional models have been presented for malaria infection in [8, 9]. The fractional model of energy supply-demand system and its stability analysis can be found in [10, 11].

The most significant benefit of using an FDE is its non-local property, which means that the next state of a system depends not only on its current state but also on all of its historical states. Despite describing differential, fractional, and functional equations, finding exact solutions to physical and practical problems is impossibly difficult. If there are exact solutions, they are often so complicated that it is not convenient to have numerical solutions. The conduct of the analytical solutions of the fractional differential equation represented by the fractional-order derivative operators is the fundamental principle in numerous stability issues. Motivated by the usage of the Mittag-Leffler functions in many areas of science and design, we present this paper.

Stanislaw Marcin Ulam introduced the HUS problem in 1940. Hyers [12] provided a brilliant answer to Ulam’s question about the stability of functional equations for the case of approximately additive mappings, where \( G_1 \) and \( G_2 \) were assumed to be Banach spaces, in 1941. Rassias proved the HUS for the additive Cauchy equation; later it was generalised by Aoki to additive mappings [13, 14]. Obbloza [15] was one of the first authors who investigated the HUS of differential equations. Wang [16] demonstrated the stability of FDEs with fractional integrals and contributed some new concepts in FDE stability. Liu et al. [17], established the HUS of linear Caputo-Fabrizio FDEs using the Laplace transform method, and [18], discussed the Mittag-Leffler-Ulam stabilities of fractional evolution equations. In 1948, Magnus Gosta Mittag-Leffler defined a new special function for divergent series that is known as MLF. Pollard [19] derived one parameter MLF. P. Humbert et al. [20, 21, 22] derived the main features of two-parameter MLF. Extension of MLF and the solution of differential equations of non-integer order are discussed in [23, 24].

The three-parameter extension of MLF was introduced by Prabhakar [25] in 1971. In 2002, Saxena [26] developed Volterra operations involving the Prabhakar function. D’Ovidio [27] provided a regularisation of the fractional derivative and named it after [28], where the features of the Prabhakar derivatives and their applications were discussed. Beghin and Orisingher’s [29] studied the relationship between Prabhakar and Wright functions. In [30], the stability region of fractional differential systems was studied using Prabhakar derivative analyses with Caputo and Riemann derivatives. Citation [31] discusses the Hilfiger-Prabhakar derivatives and their applications in time delay, the time-fractional Poisson process, and its renewal structure. See the discussion of Lyapunov type inequality
for a hybrid fractional differential equation with Prabhakar derivative in [32].
A class of nonlinear variable order FDE’s in the Caputo-Prabhakar sense was
solved by using Bernteon polynomials in [33]. Recently, HUS of linear differential
equations using FT was discussed in [34, 35, 36, 37, 38].

We establish the fractional Fourier transform and present it in integral form.
Furthermore, using the convolution concept and properties of the fractional Fourier
transform, the solution of the Mittag-Leffler-Hyers-Ulam stability conditions con-
cerning the fractional differential equation is established. In particular, we prove
the Mittag-Leffler-Hyers-Ulam stability of the following FDEs using the FrFT:

\[
\begin{aligned}
&\mathcal{D}_e^\alpha \psi, \sigma u(e) + du(e) = q(e), \quad e \in (0, Q], \quad d \in \mathbb{R} \\
&\mathcal{D}_e^\psi u(e) \mid_{e=0} = 0,
\end{aligned}
\]

and

\[
\begin{aligned}
&\mathcal{D}_e^\alpha \psi, \sigma u(e) + du(e) = \mathcal{G}(e, u(e)), \quad e \in (0, Q], \quad d \in \mathbb{R} \\
&\mathcal{D}_e^\psi u(e) \mid_{e=0} = 0,
\end{aligned}
\]

and

\[
\begin{aligned}
&\mathcal{D}_e^\alpha \psi, \sigma u(e) + du(e) = q(e), \quad e \in (0, Q], \quad d \in \mathbb{R} \\
&\mathcal{D}_e^\psi u(e) \mid_{e=0} = 0,
\end{aligned}
\]

and

\[
\begin{aligned}
&\mathcal{D}_e^\alpha \psi, \sigma u(e) + du(e) - \mathcal{G}(e, u(e)) = F(e), \quad e \in (0, Q], \quad d \in \mathbb{R} \\
&\mathcal{D}_e^\psi u(e) \mid_{e=0} = 0.
\end{aligned}
\]

The paper is organised as follows: In Section 2, basic definitions, theorems, and
lemmas related to fractional derivatives, MLF, Prabhakar derivatives, and FrFT
are given. In Sections 3 and 4, Mittag-Leffler-HUS of linear and nonlinear FDEs
is proved by using the FrFT. In Sections 5 and 6, examples and conclusions are
given.

2. Preliminaries

The Fourier transform (FT) was defined by the French mathematician Joseph
Fourier. The term fraction power for the Fourier operators appeared in 1929.
FrFTs represent the generalisation of the conventional FT. Victor Nami first
introduced the FrFT in 1980, which, due to its time-frequency characteristics,
produces better results for non-stationary signals than the FT. FrFT is used in
several scientific fields, such as optics, time-frequency distribution, image process-
ing, satellite image compression, signal image recovery and noise removal, image
smoothing, encryption and decryption. V. Namias as a way to solve FrFT plays a
very important role in solving ordinary and partial equations. The analytical so-
lutions of the FDE described by the fractional-order derivative operators play the
main role in many stability problems. Motivated by the success of the application of the MLFs in many areas of fractional calculus, we present this paper.

In this section, we state some essential definitions and lemmas used in this study.

**Definition 1.** The Riemann–Liouville derivative operator of order $\theta$ is defined by

$$D^{\theta} f(e) = \begin{cases} \frac{1}{\Gamma(n-\theta)} \frac{d^n}{d(e-Q)^{\theta+n-1}} f(e), & n-1 < \theta < n, n \in \mathbb{N} \\ \frac{d^n}{d(e)^{\theta+n-1}} f(e), & \theta = n \in \mathbb{N}, \end{cases}$$

where $\theta > 0$, $Q > a$, $\theta, a, e \in \mathbb{R}$.

**Definition 2.** The Mittag–Leffler function can be defined in terms of a power series as

$$E_{\theta}(x) = \sum_{k=0}^{\infty} \frac{x^k}{\Gamma(\theta k + 1)}, \quad \theta > 0, \quad \text{(one parameter)} \quad (1)$$

$$E_{\theta,\tau}(x) = \sum_{k=0}^{\infty} \frac{x^k}{\Gamma(\tau \theta + k)}, \quad \tau > 0, \theta > 0 \quad \text{(two parameters).} \quad (2)$$

**Definition 3.** The generalized MLF with three-parameters was introduced by Prabhakar (known as the Prabhakar function) as

$$E_{\varsigma,\tau,\phi}^{\phi}(z) = \sum_{k=0}^{\infty} \frac{(\phi)_k z^k}{\Gamma(\varsigma k + \tau)}$$

or

$$E_{\varsigma,\tau,\phi}^{\phi}(z) = \frac{1}{\Gamma(\phi)} \sum_{k=0}^{\infty} \frac{\Gamma(\phi + k)}{k! \Gamma(\varsigma k + \tau)} z^k,$$

where $z, \varsigma, \tau, \phi \in \mathbb{C}$, $\Re(\varsigma) > 0, \Re(\tau) > 0, \Re(\phi) > 0$. Here

$$(\phi)_k = \phi(\phi + 1)(\phi + 2)......(\phi + k - 1) = \frac{\Gamma(\phi + k)}{\Gamma(\phi)}, \quad (\phi)_0 = 1, \phi \neq 0$$

is a Pochhammer symbol.

**Definition 4.** The Prabhakar integral operator and Prabhakar derivative including the generalized MLF are defined as follows:

$$E_{\phi,\psi,w,0+}^{\phi}(e) = \int_{0}^{e} (e - u)^{w-1} E_{\phi,\psi}(w(e - u)^{\phi}) f(u) du$$
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and
\[ D_{\varphi, \psi, w, 0}^{\alpha} f(e) = \frac{d^m}{de^m} E_{\varphi, m - \psi, w, 0}^{-\alpha} f(e), \]
where \( 0 < \alpha < \beta \leq \infty; \varphi, \psi, w, \alpha \in \mathbb{C}, R(\varphi), R(\psi) > 0. \)

**Lemma 1.** Let \( \varphi, \varrho, \psi, \sigma \in \mathbb{C} \) with \( R(\psi) > 0. \) Then the differentiation of the generalized MLF is given by
\[
\left( \frac{d}{dx} \right)^n \left[ x^{\psi-1} E_{\varphi, \psi}^{\sigma \varphi} (e^{x^p}) \right] = x^{\psi-n-1} E_{\varphi, \psi-n}^{\sigma \varphi} (e^{x^p}), \quad \text{for any } n \in \mathbb{N}.
\]

**Lemma 2.** The generalized MLF
\[
S = \sum_{n=0}^{\infty} e^{\psi n} E_{\varphi, \psi}^{n + \varphi} (e^{\sigma e}), \quad e \in \mathbb{C}, w, \varrho \in \mathbb{R}
\]
is absolutely convergent, where \( R(\varrho), R(\psi) > 0. \)

**Lemma 3.** Let
\[
\mathcal{C}_{1-\psi}[a, Q] = \left\{ u(e) \in \mathcal{C}[a, Q]; e^{1-\psi} u(e) \in \mathcal{C}[a, Q] \right\}, 0 < \psi < 1
\]
and
\[
\lim_{e \to a^+} [(t-a)^{1-\psi} u(e)] = c, \quad c \in \mathbb{C}.
\]
Then
\[
\left( E_{\varphi 1-\psi, \sigma, a}^{\alpha} u \right) (a^+) = c \Gamma(\psi)
\]
holds. Also, let
\[
\left( E_{\varphi 1-\psi, \sigma, a}^{\alpha} u \right) (a^+) = \chi, \quad \chi \in \mathcal{C}
\]
and \( \lim_{e \to a^+} [(t-a)^{1-\psi} u(e)] \). Then
\[
\lim_{e \to a^+} [(t-a)^{1-\psi} u(e)] = \frac{b}{\Gamma(\psi)}.
\]

**Definition 5.** For a function \( u \in \phi \in (R) \), the FrFT of the order \( \zeta (0 < \zeta \leq 1) \), \( \hat{u}_{\zeta} \)
is defined as
\[
\hat{u}_{\zeta} = (\mathcal{F}_{\zeta} u)(\Omega) = \int_{-\infty}^{\infty} u(e) \mathcal{E}_{\zeta}(\Omega, e) de, \quad \Omega \in \mathbb{R},
\]
where
\[
\mathcal{E}_{\zeta}(\Omega, e) = \begin{cases} e^{-i|\Omega|^{\frac{1}{\zeta}} e}, & \Omega \leq 0 \\ e^{i|\Omega|^{\frac{1}{\zeta}} e}, & \Omega \geq 0. \end{cases}
\]
If $\varsigma = 1$, the kernel $E_1$ is defined by the kernel of the conventional FT

$$E_1(\Omega, e) = \begin{cases} e^{-i|\Omega|e}, & \Omega \leq 0, \\ e^{i|\Omega|e}, & \Omega \geq 0, \end{cases} = e^{i|\Omega|}, \, \Omega, e \in \mathbb{R}.$$ 

This means that the FrFT of the order 1 is a conventional FT.

**Definition 6.** Let $f, g \in \mathbb{R} \rightarrow \mathbb{F}$ be continuous and $f^* g^*$ be piece-wise continuous. If $F(f(x)) = F(g(x))$, then $f(x) = g(x)$ for every $x$.

**Definition 7.** The FrFT of the convolution of $f(x)$ and $g(x)$ is a product of the FrFT of $f(x)$ and $g(x)$. Let $k, u \in \phi(\mathbb{R})$ and $\varsigma > 0$. Then for any $\Omega \in \mathbb{R},$

$$(F_\varsigma(k \ast u)(\Omega)) = (F_\varsigma(k)(\Omega))(F_\varsigma(u)(\Omega)).$$

In particular

$$(F(k \ast u))(\Omega) = (Fk)(\Omega)(Fu)(\Omega), (\Omega \in \mathbb{R}).$$

The convolution in the time domain is equivalent to the multiplication in the frequency domain.

**Remark 1.** Let $\tau \in \mathbb{C}, \mathbb{R}(\tau) > 0, Q > 0$. Then

$$F_\varsigma(e^\tau) = \frac{\Gamma(\tau + 1)}{(-i\Omega^{1/\varsigma})^{\tau+1}}.$$ 

**Theorem 1.** Let $\phi, \tau \in \mathbb{C}, \mathbb{R}(\phi) > 0, \mathbb{R}(\tau) > 0, \sigma \in \mathbb{R}$. Then

$$F_\varsigma\left(e^{\sigma m + \tau - 1}E_{\phi, \tau}^{\sigma}(\sigma e^{\phi})\right) = \frac{(-i\Omega^{1/\varsigma})^{\sigma - \tau} m!}{\left((-i\Omega^{1/\varsigma})^\sigma - \sigma\right)^{m+1}}$$

holds.

**Lemma 4.** The FrFT of Prabhakar integral is given by

$$F_\varsigma \left[E_{\phi, \psi, \sigma, 0+}^\varsigma f(e)\right] = \left(-i\Omega^{1/\varsigma}\right)^{-\psi} \left[1 - \sigma(-i\Omega^{1/\varsigma})^{-\sigma} F_\varsigma(-i\Omega^{1/\varsigma})\right].$$

**Proof.** We know that the Prabhakar integral operator including the generalized MLF is

$$E_{\phi, \psi, \sigma, 0+}^\varsigma f(e) = \int_0^e (e - u)^{u-1}E_{\phi, \psi}^\varsigma(\sigma(e - u)^{\phi}) f(u) du, \, e > 0.$$
Taking FrFT on both sides, we have

\[
F_\varsigma \left[ \mathcal{E}_{\varrho,\psi,\sigma,0}^{\vartheta} f(e) \right] = F_\varsigma \left[ \int_0^e (e - u)^{\psi-1} \mathcal{E}_{\varrho,\psi}^{\vartheta} [\sigma (e - u)^{\vartheta}] f(u) du \right]
\]

\[
= F_\varsigma \left[ e^{\psi-1} \mathcal{E}_{\varrho,\psi}^{\vartheta} (\sigma e^\vartheta) \right] F_\varsigma [f(e)]
\]

\[
= F_\varsigma \left[ e^{\psi-1} \sum_{k=0}^{\infty} \frac{(\sigma e^\vartheta)^k}{k!} \Gamma(\varrho k + \psi) \right] F_\varsigma [f(e)]
\]

\[
= \sum_{k=0}^{\infty} \frac{(\sigma e^\vartheta)^k}{k!} \frac{\Gamma(\varrho k + \psi)}{\Gamma(\varrho k + \psi + \varrho)} F_\varsigma [f(e)]
\]

\[
= \sum_{k=0}^{\infty} \frac{(\sigma e^\vartheta)^k}{k!} \frac{\Gamma(\varrho k + \psi)}{\Gamma(\varrho k + \psi + \varrho)} \left( -i \Omega_{\varsigma}^{\frac{1}{\varrho}} \right)^{-\varrho k} (-i \Omega_{\varsigma}^{\frac{1}{\varrho}})^{-\psi} F_\varsigma [f(e)]
\]

\[
= \left( -i \Omega_{\varsigma}^{\frac{1}{\varrho}} \right)^{-\psi} \sum_{k=0}^{\infty} \frac{(\sigma e^\vartheta)^k}{k!} \frac{\Gamma(\varrho k + \psi)}{\Gamma(\varrho k + \psi + \varrho)} \left( -i \Omega_{\varsigma}^{\frac{1}{\varrho}} \right)^{-\varrho k} F_\varsigma [f(e)].
\]

Expanding the summation, we have

\[
F_\varsigma \left[ \mathcal{E}_{\varrho,\psi,\sigma,0}^{\vartheta} f(e) \right] = \left( -i \Omega_{\varsigma}^{\frac{1}{\varrho}} \right)^{-\psi} \left[ 1 - \sigma \left( -i \Omega_{\varsigma}^{\frac{1}{\varrho}} \right)^{-\varrho} \right]^{-\vartheta} F_\varsigma [f(e)].
\]

\[\blacktriangleup\]

**Lemma 5.** The FrFT of Prabhakar derivative has the form

\[
F_\varsigma \left[ \mathcal{D}_{\varrho,\psi,\sigma,0}^{\vartheta} f(e) \right] = \left( -i \Omega_{\varsigma}^{\frac{1}{\varrho}} \right)^{\psi} \left[ 1 - \sigma \left( -i \Omega_{\varsigma}^{\frac{1}{\varrho}} \right)^{-\varrho} \right]^{-\vartheta} F_\varsigma [f(e)], \quad -1 \leq \psi \leq m.
\]

**Proof.** We know that, the Prabhakar derivative is

\[
\mathcal{D}_{\varrho,\psi,\sigma,0}^{\vartheta} f(e) = \frac{d^m}{de^m} \mathcal{D}_{\varrho,\psi,\sigma,0}^{m-\vartheta} f(e).
\]

Taking FrFT on both sides, we have

\[
F_\varsigma \left[ \mathcal{D}_{\varrho,\psi,\sigma,0}^{\vartheta} f(e) \right] = F_\varsigma \left[ \frac{d^m}{de^m} \mathcal{D}_{\varrho,\psi,\sigma,0}^{m-\vartheta} f(e) \right]
\]

\[
= F_\varsigma \left[ \frac{d^m}{de^m} \int_0^e (e - u)^{m-\vartheta-1} \mathcal{E}_{\varrho,\psi,\sigma,0}^{\vartheta} [\sigma (e - u)^{\vartheta}] f(u) du \right]
\]
Expanding the summation, we have

\[
F_\varsigma \left[ D_0^\varphi \rho, \psi, \sigma, 0+ f(e) \right] = (-i \Omega_1^\varphi)^\psi \left[ 1 - \sigma (-i \Omega_1^\varphi)^{-\sigma} \right] F_\varsigma [f(e)].
\]

\[
\Box
\]


In this section, we are going to prove Mittag-Leffler HUS for linear and non-linear FDEs

\[
\begin{align*}
\mathcal{D}_0^\varphi \rho, \psi, \sigma u(e) + du(e) &= q(e), \quad e \in (0, Q], \quad d \in \mathbb{R} \\
\left. e^{\psi-1} u(e) \right|_{e=0},
\end{align*}
\]

\[
\begin{align*}
\mathcal{D}_0^\varphi \rho, \psi, \sigma u(e) + du(e) &= \mathcal{G}(t, u(e)), \quad e \in (0, Q], \quad d \in \mathbb{R} \\
\left. e^{\psi-1} u(e) \right|_{e=0}
\end{align*}
\]

with Prabhakar derivatives using FrFT.
3.1. Stability of linear FDE $D_{\varphi,\psi,\sigma}^\alpha u(e) + du(e) = q(e)$, $e \in (0, Q]$, $d \in \mathbb{R}$ and $e^{\psi-1}u(e)|_{e=0}$

**Definition 8.** The FDE

$$\varphi \{ q(e), u(e), D_{\varphi_1,\psi_1,\sigma}^\alpha u, \ldots, D_{\varphi_n,\psi_n,\sigma,0+}^\alpha u \} = 0, \quad \phi_i \geq 0, \quad i = 1 \text{ to } n$$

has HUS if

$$\left| \varphi \{ q(e), u(e), D_{\varphi_1,\psi_1,\sigma}^\alpha u, \ldots, D_{\varphi_n,\psi_n,\sigma,0+}^\alpha u \} \right| \leq \varepsilon, \quad \text{for any } \varepsilon > 0.$$  

Then there exists a solution $u_a$ of the FDE such that

$$|u(e) - u_a(e)| \leq K(\varepsilon)$$

and

$$\lim_{\varepsilon \to 0} K(\varepsilon) = 0.$$

**Theorem 2.** Let $u(e) \in C_{1-\psi}[0, Q]$ and $u(e)$ satisfy

$$|D_{\varphi,\psi,w}^\alpha u + du(e) - q(e)| \leq \varepsilon, \quad 0 < \psi < 1, \quad d \in \mathbb{R}. \quad (3)$$

Then there exists a solution $u_a(e) : (0, Q] \to C$ of FDE

$$D_{\varphi,\psi,w}^\alpha u + du(e) = q(e) \quad (4)$$

such that

$$|u(e) - u_a(e)| \leq \frac{\varepsilon e^\psi}{|d|} \sum_{n=0}^{\infty} \frac{e^{\psi n} E_{\varphi,\psi,n+\psi+1}(|\sigma|e^\psi)}{|d|^n},$$

where $E_{\varphi,\psi,n+\psi+1}(|\sigma|e^\psi)$ is the generalized MLF.

**Proof.** For all $e \in (0, Q]$, we consider

$$y(e) = D_{\varphi,\psi,w}^\alpha u + du(e) - q(e).$$

Taking FrFT on both sides, we get

$$F_{\zeta}[y(e)] = F_{\zeta}[D_{\varphi,\psi,w}^\alpha u] + F_{\zeta}[du(e)] - F_{\zeta}[q(e)]$$

$$= \left( -i\Omega_{\zeta}^{\psi} \right)^{\psi} \left[ 1 - \sigma \left( -i\Omega_{\zeta}^{\psi} \right)^{-\sigma} \right]^0 F_{\zeta}[u(e)]$$

$$- \left( E_{\varphi,1-\psi,\sigma,0+}^\alpha u \right)(0) + dF_{\zeta}[u(e)] - F_{\zeta}[q(e)].$$
By using Lemma 3 and considering $b = du_0 \Gamma(\psi)$ and $c = \frac{b}{d(\psi)}$, we get

$$F_\varsigma[y(e)] = \left(-i\Omega\right)^\psi \left[1 - \sigma \left(-i\Omega\right)^{-\psi}\right] F_\varsigma[u(e)] - du_0 \Gamma(u) + dF_\varsigma[u(e)] - F_\varsigma[q(e)]$$

$$F_\varsigma[y(e)] = \left(-i\Omega\right)^\psi \left[1 - \sigma \left(-i\Omega\right)^{-\psi}\right] + d \right) F_\varsigma[u(e)] - du_0 \Gamma(u) - F_\varsigma[q(e)]$$

$$F_\varsigma[u(e)] = \left(\frac{du_0 \Gamma(\psi)}{d(\psi)} + F_\varsigma[q(e)]\right)$$

$$(5)$$

At this point, by setting $u_a(e) = du_0 \Gamma(\psi) \sum_{n=0}^{\infty} \left(-\frac{1}{d}\right)^n \int_0^e q(x)(e-x)^{\psi+n+\psi-1}\mathcal{E}_{\psi+n+\psi}(\sigma e^\psi) dx / d \right)$

we have

$$e^{1-\psi} u_a(e) = \frac{du_0 \Gamma(\psi) \sum_{n=0}^{\infty} \left(-\frac{1}{d}\right)^n \int_0^e q(x)(e-x)^{\psi+n+\psi-1}\mathcal{E}_{\psi+n+\psi}(\sigma e^\psi) dx / d \right) \right.$$  

This implies that $u_a(e)$ satisfies

$$(6)$$

$$e^{1-\psi} u_a(e)|_{e=0}.$$  

Now, applying FrFTT and using the convolution property, we have

$$F_\varsigma[u(a)] = F_\varsigma \left[ \frac{du_0 \Gamma(\psi) \sum_{n=0}^{\infty} \left(-\frac{1}{d}\right)^n \int_0^e q(x)(e-x)^{\psi+n+\psi-1}\mathcal{E}_{\psi+n+\psi}(\sigma e^\psi) dx / d \right] \right.$$  

$$+ F_\varsigma \left[ \frac{\sum_{n=0}^{\infty} \left(-\frac{1}{d}\right)^n \int_0^e q(x)(e-x)^{\psi+n+\psi-1}\mathcal{E}_{\psi+n+\psi}(\sigma e^\psi) dx / d \right] \right.$$  

(7)
Expanding the summation, we get

\[
F\left[u_a(e)\right] = \frac{d u_0 \Gamma(u)}{d} + F_\psi[q(e)] \left\{ \frac{d u_0 \Gamma(u) + F_\psi[q(e)]}{\left( -i \Omega_1^1 \right)^\psi \left[ 1 - \sigma \left( -i \Omega_1^1 \right)^{-\varphi} \right]^\varphi + d } \right\}.
\]

Taking (7) into account, we deduce that \( u_a(e) \) is a solution of (4).

By subtracting (5) and (7) from each other, we have

\[
F\left[u(e)\right] + F\left[u_a(e)\right] = \left\{ \left( -i \Omega_1^1 \right)^\psi \left[ 1 - \sigma \left( -i \Omega_1^1 \right)^{-\varphi} \right]^\varphi + d \right\}.
\]

\[
F\left[u(e)\right] + F\left[u_a(e)\right] = \frac{F\left[y(e)\right]}{\left( -i \Omega_1^1 \right)^\psi \left[ 1 - \sigma \left( -i \Omega_1^1 \right)^{-\varphi} \right]^\varphi + d }.
\]
By Lemma 4, the LHS of (8) implies

\[ F_{\varsigma} \left[ \sum_{n=0}^{\infty} \left( -\frac{1}{d} \right)^n e^{\psi n} \mathcal{E}_{\varsigma,\psi n+\psi}^{\sigma e^\theta} \right] * y(e) \]

\[ = F_{\varsigma} \left[ \sum_{n=0}^{\infty} \left( -\frac{1}{d} \right)^n e^{\psi n} \mathcal{E}_{\varsigma,\psi n+\psi}^{\sigma e^\theta} \right] F_{\varsigma} [y(e)] \]

\[ = \frac{F_{\varsigma} [y(e)]}{\left( \left( -i \Omega \right)^{\psi} \left( 1 - \sigma \left( -i \Omega \right)^{1-\psi} \right)^{\sigma} + d \right).} \]

Hence, (8) can be written as

\[ F_{\varsigma} [u(e)] + F_{\varsigma} [u_a(e)] = F_{\varsigma} \left[ \sum_{n=0}^{\infty} \left( -\frac{1}{d} \right)^n e^{\psi n} \mathcal{E}_{\varsigma,\psi n+\psi}^{\sigma e^\theta} \right] * y(e) \]

Finally, (3) implies

\[ |u(e) + u_a(e)| = \left| \sum_{n=0}^{\infty} \left( -\frac{1}{d} \right)^n e^{\psi n} \mathcal{E}_{\varsigma,\psi n+\psi}^{\sigma e^\theta} \right| * y(e) \]

\[ = \frac{\varepsilon e^\psi}{|d|} \sum_{n=0}^{\infty} \frac{e^{\psi n} \mathcal{E}_{\varsigma,\psi n+\psi+1}^{\sigma e^\theta}}{|d|^n}, \]

where \( \mathcal{E}_{\varsigma,\psi n+\psi}^{\sigma e^\theta} \) is the generalized MLF.

By the definition of the HUS theorem, the FDE (3) has Mittag-Leffler-Hyers–Ulam Stability.

3.2. Stability of Non-linear FDE

\[ \mathcal{D}_{\omega,\psi,\sigma} u(e) + du(e) = \mathcal{G}(t, u(e)), e \in (0, Q], \quad d \in \mathbb{R} \text{ and } e^{1-\psi} u(e)|_{e=0} \]

Definition 9. For \( \mathcal{G} : [0, Q] \times \mathbb{R} \rightarrow \mathbb{R} \), the FDE

\[ \varphi \left\{ \mathcal{G}(t, u(e)), u(e), \mathcal{D}_{\omega_1,\psi_1,\sigma}^{\phi_1} u, \ldots, \mathcal{D}_{\omega_n,\psi_n,\sigma}^{\phi_n} u \right\} = 0, \quad \phi_i \geq 0, i = 1 \text{ to } n \]

has HUS if

\[ \left| \varphi \left\{ \mathcal{G}(t, u(e)), u(e), \mathcal{D}_{\omega_1,\psi_1,\sigma}^{\phi_1} u, \ldots, \mathcal{D}_{\omega_n,\psi_n,\sigma}^{\phi_n} u \right\} \right| \leq \varepsilon, \quad \text{for any } \varepsilon > 0. \]
Then there exists a solution $u_a$ of the FDE such that
\[ |u(e) - u_a(e)| \leq K(\varepsilon) \]
and
\[ \lim_{\varepsilon \to 0} K(\varepsilon) = 0. \]

**Theorem 3.** Let $\mathcal{G}: [0, Q] \times \mathbb{R} \to \mathbb{R}$, $u(e) \in C_{1-\psi}[0, Q]$ and $u(e)$ satisfy
\[ |D_{\varrho, \psi, w}^a u + du(e) - \mathcal{G}(t, u(e))| \leq \varepsilon, \quad 0 < \psi < 1, \quad d \in \mathbb{R}. \]
Then there exists a solution $u_a(e):(0, Q] \to \mathcal{C}$ of FDE such that
\[ D_{\varrho, \psi, w}^a u + du(e) = \mathcal{G}(t, u(e)) \]
and
\[ |u(e) - u_a(e)| \leq \varepsilon e^{\psi} \sum_{n=0}^{\infty} \frac{e^{\psi n + (\psi + 1)}(|\sigma|^e)^n}{|d|^n}, \]
where $E_{\psi, \psi + 1}^{\psi + \alpha} (|\sigma|^e)$ is the generalized MLF.

**Proof.** The proof is similar to that of Theorem 2. ▶


In this section, we are going to prove Mittag-Leffler-HUS for linear and nonlinear FDEs
\[
\begin{cases}
D_{\varrho, \psi, \sigma}^a u(e) + du(e) - q(e) = F(e), & e \in (0, Q], \ d \in \mathbb{R} \\
e^{\psi-1}u(e)|_e=0,
\end{cases}
\]
\[
\begin{cases}
D_{\varrho, \psi, \sigma}^a u(e) + du(e) - \mathcal{G}(t, u(e)) = F(e), & e \in (0, Q], \ d \in \mathbb{R} \\
e^{1-\psi}u(e)|_e=0
\end{cases}
\]
with Prabhakar derivatives using FrFT.

4.1. Stability of linear FDE $D_{\varrho, \psi, \sigma}^a u(e) + du(e) - q(e) = F(e), e \in (0, Q], \ d \in \mathbb{R}$ and $e^{\psi-1}u(e)|_e=0$

**Theorem 4.** If a function $u(e)$ satisfies
\[ |D_{\varrho, \psi, w}^{a_1} u + du(e) - q(e)| \leq F(e), \ 0 < \psi < 1, \ d \in \mathbb{R}, \ \forall \ e \in C_{1-\psi}[0, Q], \ F(e) > 0, \]
(9)
then there exists a solution \( u_a(e) : (0, \mathcal{Q}) \rightarrow \mathcal{C} \) of FDE such that
\[
D_{\varrho,\psi,w}^\alpha u + du(e) - q(e) = F(e) \tag{10}
\]
and
\[
|u(e) - u_a(e)| \leq \frac{F(e)}{|d|} \sum_{n=0}^{\infty} e^{\psi n} E_{\varrho,\psi,w+1} (|\sigma| e^\varrho) |d|^n.
\]

**Proof.** Consider
\[
y(e) = D_{\varrho,\psi,w}^\alpha u + du(e) - q(e) - F(e), \ e \in (0, \mathcal{Q}).
\]
Taking FrFT on both sides, we get
\[
F_\varsigma[y(e)] = F_\varsigma[D_{\varrho,\psi,w}^\alpha u] + F_\varsigma[du(e)] - F_\varsigma[q(e)] - F_\varsigma[F(e)]
\]
\[
= \left(-i\Omega_1^\varsigma\right)^\psi \left[1 - \sigma \left(-i\Omega_1^\varsigma\right)^\varrho\right]^a F_\varsigma[u(e)]
\]
\[
- \left(E_{\varrho,\psi,w+1}^\varsigma\right) (0) + dF_\varsigma[u(e)] - F_\varsigma[q(e)] - F_\varsigma[F(e)].
\]
By using Lemma 3 and considering \( b = du_0 \Gamma(\psi) \) and \( c = \frac{b}{a(\psi^2)} t \), we get
\[
F_\varsigma[y(e)] = \left(-i\Omega_1^\varsigma\right)^\psi \left[1 - \sigma \left(-i\Omega_1^\varsigma\right)^\varrho\right]^a F_\varsigma[u(e)]
\]
\[
- du_0 \Gamma(u) + dF_\varsigma[u(e)] - F_\varsigma[q(e)] - F_\varsigma[F(e)]
\]
\[
F_\varsigma[y(e)] = \left\{ \left(-i\Omega_1^\varsigma\right)^\psi \left[1 - \sigma \left(-i\Omega_1^\varsigma\right)^\varrho\right]^a + d \right\} F_\varsigma[u(e)]
\]
\[
- du_0 \Gamma(u) - F_\varsigma[q(e)] - F_\varsigma[F(e)]
\]
\[
F_\varsigma[u(e)] = \frac{F_\varsigma[y(e)]}{\left\{ \left(-i\Omega_1^\varsigma\right)^\psi \left[1 - \sigma \left(-i\Omega_1^\varsigma\right)^\varrho\right]^a + d \right\}} + \frac{du_0 \Gamma(u) + F_\varsigma[q(e)] + F_\varsigma[F(e)]}{\left\{ \left(-i\Omega_1^\varsigma\right)^\psi \left[1 - \sigma \left(-i\Omega_1^\varsigma\right)^\varrho\right]^a + d \right\}}. \tag{11}
\]
Let \( u_n(e) \) be the solution of FDE. Then
\[
\mathcal{C}_{1-\psi}[a, \mathcal{Q}] = \left\{ u(e) \in \mathcal{C}[a, \mathcal{Q}]; e^{1-\psi} u_n(e) \in \mathcal{C}[a, \mathcal{Q}] \right\}, 0 < \psi < 1
\]
and

\[ \lim_{e \to a^+} [(t - a)^{1-\psi}u_a(e)] = c, \quad c \in \mathcal{C}. \]

Consequently

\[ \left( \mathcal{F}^{-\psi}_{\psi, a^+} u \right) (a^+) = c \Gamma(\psi) \]

holds. Therefore,

\[
u_a(e) = \frac{du_0 \Gamma(u) \sum_{n=0}^{\infty} \left( \frac{-1}{d} \right)^n e^{\psi n + \psi} - 1 \mathcal{E}^n_{\psi, \psi n + \psi} \sigma(e^\psi)}{d} 
+ \sum_{n=0}^{\infty} \left( \frac{-1}{d} \right)^n \int_0^e q(x)(e - x)^{\psi n + \psi - 1} \mathcal{E}^n_{\psi, \psi n + \psi} \sigma(e - x^\psi) dx 
+ \sum_{n=0}^{\infty} \left( \frac{-1}{d} \right)^n \int_0^e F(x)(e - x)^{\psi n + \psi - 1} \mathcal{E}^n_{\psi, \psi n + \psi} \sigma(e - x^\psi) dx \]

(12)

We have

\[
e^{1-\psi}u_a(e) = \frac{du_0 \Gamma(u) \sum_{n=0}^{\infty} \left( \frac{-1}{d} \right)^n e^{\psi n} \mathcal{E}^n_{\psi, \psi n + \psi} \sigma(e^\psi)}{d} 
+ \sum_{n=0}^{\infty} \left( \frac{-1}{d} \right)^n \int_0^e q(x)(e - x)^{\psi n + \psi - 1} \mathcal{E}^n_{\psi, \psi n + \psi} \sigma(e - x^\psi) dx 
+ \sum_{n=0}^{\infty} \left( \frac{-1}{d} \right)^n \int_0^e F(x)(e - x)^{\psi n + \psi - 1} \mathcal{E}^n_{\psi, \psi n + \psi} \sigma(e - x^\psi) dx \]

This implies that \( u_a(e) \) satisfies \( e^{1-\psi}u_a(e)|_{e=0} = 0 \).

Now, applying FrFT and using the convolution property, we have

\[
F_\zeta [u_a(e)] = F_\zeta \left[ \frac{du_0 \Gamma(u) \sum_{n=0}^{\infty} \left( \frac{-1}{d} \right)^n e^{\psi n + \psi} - 1 \mathcal{E}^n_{\psi, \psi n + \psi} \sigma(e^\psi)}{d} 
+ \sum_{n=0}^{\infty} \left( \frac{-1}{d} \right)^n \int_0^e q(x)(e - x)^{\psi n + \psi - 1} \mathcal{E}^n_{\psi, \psi n + \psi} \sigma(e - x^\psi) dx 
+ \sum_{n=0}^{\infty} \left( \frac{-1}{d} \right)^n \int_0^e F(x)(e - x)^{\psi n + \psi - 1} \mathcal{E}^n_{\psi, \psi n + \psi} \sigma(e - x^\psi) dx \right] 
= \frac{du_0 \Gamma(u) \sum_{n=0}^{\infty} \left( \frac{-1}{d} \right)^n e^{\psi n + \psi} - 1 \mathcal{E}^n_{\psi, \psi n + \psi} \sigma(e^\psi)}{d} 
+ \sum_{n=0}^{\infty} \left( \frac{-1}{d} \right)^n \int_0^e q(x)(e - x)^{\psi n + \psi - 1} \mathcal{E}^n_{\psi, \psi n + \psi} \sigma(e - x^\psi) dx 
+ \sum_{n=0}^{\infty} \left( \frac{-1}{d} \right)^n \int_0^e F(x)(e - x)^{\psi n + \psi - 1} \mathcal{E}^n_{\psi, \psi n + \psi} \sigma(e - x^\psi) dx \right]
\]
Expanding the summation, we get

\[
F_c \left[ u_a(e) \right] = \frac{\sum_{n=0}^{\infty} \left( \frac{-1}{d} \right)^n F_c \left[ e^{\psi n + \psi - 1} E^{an + \sigma}_{\psi n + \psi} (\sigma e^\psi) \right]}{du_0 \Gamma (u) + F_c [q(e)] + F_c [F(e)]}.
\]

Subtracting (11) and (13) from each other, we get

\[
\left( -i\Omega^{\frac{1}{2}} \right)^\psi \left[ 1 - \sigma \left( -i\Omega^{\frac{1}{2}} \right)^{-\psi} \right]^a + d
\]

Taking (13) into account, we deduce that \( u_a(e) \) is a solution of (10). Subtracting (11) and (13) from each other, we get

\[
F_c \left[ u_a(e) \right] + F_c \left[ u(e) \right] = \left( -i\Omega^{\frac{1}{2}} \right)^\psi \left[ 1 - \sigma \left( -i\Omega^{\frac{1}{2}} \right)^{-\psi} \right]^a + d.
\]
\[
F_\varsigma [u(e)] + F_\varsigma [u_a(e)] = \frac{F_\varsigma [y(e)]}{\left\{ \left( -i\Omega_{1}^\varsigma \right)^{\psi} \left[ 1 - \sigma \left( -i\Omega_{1}^\varsigma \right)^{-\psi} \right]^{\varsigma} + d \right\}}.
\]

By Lemma 4, the RHS of (14) implies

\[
F_\varsigma \left[ \sum_{n=0}^{\infty} \left( -\frac{1}{d} \right)^{n} e^{\psi n} \mathcal{G}_{\psi, n+\psi}^{\psi+\varphi}(\sigma e^{\psi}) \right] = F_\varsigma [y(e)]
\]

\[
= \frac{F_\varsigma [y(e)]}{\left\{ \left( -i\Omega_{1}^\varsigma \right)^{\psi} \left[ 1 - \sigma \left( -i\Omega_{1}^\varsigma \right)^{-\psi} \right]^{\varsigma} + d \right\}}.
\]

Hence, (14) can be written as

\[
F_\varsigma [u(e)] + F_\varsigma [u_a(e)] = F_\varsigma \left[ \sum_{n=0}^{\infty} \left( -\frac{1}{d} \right)^{n} e^{\psi n} \mathcal{G}_{\psi, n+\psi}^{\psi+\varphi}(\sigma e^{\psi}) \right] * y(e).
\]

Finally, from (9) we get

\[
|u(e) + u_a(e)| = \left| \sum_{n=0}^{\infty} \left( -\frac{1}{d} \right)^{n} e^{\psi n} \mathcal{G}_{\psi, n+\psi}^{\psi+\varphi}(\sigma e^{\psi}) * y(e) \right|
\]

\[
= \frac{F(e) e^{\psi}}{|d|} \sum_{n=0}^{\infty} \left| e^{\psi n} \mathcal{G}_{\psi, n+\psi}^{\psi+\varphi}(\sigma e^{\psi}) \right|^{n},
\]

where \( \mathcal{G}_{\psi, n+\psi}^{\psi+\varphi}(\sigma e^{\psi}) \) is the generalized MLF.

By the definition of the HUS theorem, the FDE (3) has Mittag-Leffler-Hyers–Ulam Stability.

### 4.2. Stability of Non-linear FDE

\[
D_{\psi, \sigma}^{\varphi} u(e) + du(e) - G(t, u(e)) = F(e), \quad e \in (0, Q], \quad d \in \mathbb{R} \quad \text{and} \quad e^{\psi-1}u(e)\big|_{e=0}
\]

**Theorem 5.** Let \( G : [0, Q] \times \mathbb{R} \to \mathbb{R} \), \( u(e) \in C_{1-\psi}[0, Q] \) and \( u(e) \) satisfy

\[
|D_{\psi, \sigma}^{\varphi} u + du(e) - G(t, u(e))| \leq F(e), \quad 0 < \psi < 1, \quad d \in \mathbb{R}.
\]

(15)
Then there exists a solution $u_\alpha(e) : (0, \mathcal{Q}] \to \mathcal{C}$ of FDE such that

$$D^{\alpha_1}_{\psi, \psi, \psi} u + d u(e) - \mathcal{G}(t, u(e)) = F(e)$$

and

$$|u(e) - u_\alpha(e)| \leq \frac{F(e) e^{\psi}}{|d|} \sum_{n=0}^{\infty} e^{\psi n} e^{\psi n + \psi} \frac{(|e| e^\psi)}{|d|^n}.$$

**Proof.** The proof is similar to that of Theorem 4. ▮

5. Example

Let us consider the FDE

$$D^{1.1}_{1.2.1} u(e) + 6u(e) = \frac{5\sqrt{e^t}}{2} + 6e^{\frac{1}{2}} + \frac{1}{16},$$

where $\psi = 1$, $\varrho = 1$, $\delta = 1$ and $q(e) = \frac{5\sqrt{e^t}}{2} + 6e^{\frac{1}{2}} + \frac{1}{16}$.

For $\varepsilon = \frac{1}{8}$, the function $u(e)$ satisfies

$$\left| D^{1.1}_{1.2.1} u(e) + 6u(e) - \frac{5\sqrt{e^t}}{2} + 6e^{\frac{1}{2}} + \frac{1}{16} \right| \leq \frac{1}{8}$$

and the initial condition is $e^{1/2} u(e)|_{e=0}$. The exact solution of (17) is

$$u_\varsigma(e) = \frac{1}{6} \sum_{n=0}^{\infty} \left( \frac{-1}{7} \right)^n \int_0^e \left( \frac{5\sqrt{e^t}}{2} + 6e^{\frac{1}{2}} + \frac{1}{16} \right) (e - x)^{\frac{1}{2}n - \frac{1}{2}} e^{\frac{1}{12}n + \frac{3}{2}} (e - x) dx$$

and the approximate solution $u_1(e)$ is

$$|u_1(e) - u_\varsigma(e)| < \frac{e^{\frac{1}{2}}}{|d|} \sum_{n=0}^{\infty} \frac{e^{\frac{1}{2}n} e^{\frac{1}{12}n + \frac{3}{2}} (e)}{|6|^n}.$$

So

$$e^{\frac{1}{2}} \sum_{n=0}^{\infty} \frac{e^{\frac{1}{2}n} e^{\frac{1}{12}n + \frac{3}{2}} (e)}{|6|^n}$$

is the control function of $u_1(e)$. 
6. Conclusion

In this paper, we investigate Prabhakar derivatives in the sense of fractional calculus to find their generalized transforms. These derivatives are further generalization of fractional derivatives and effectively applicable for various applications like Cauchy problems, heat transfer problem. In order to explain the obtained results, some examples were given. Also, we introduced some standard approaches to the definition of Prabhakar derivatives, fractional differential equations, the Riemann-Liouville fractional differential operator, and the Mittag-Leffler function and studied their basic properties. In particular, we formulate the theorem describing the structure of the Mittag-Leffler-Hyers-Ulam problem for linear and nonlinear fractional differential equations associated with the Prabhakar derivatives and derive the Prabhakar derivative step response functions of those generalised systems. We discussed the basic properties of derivatives, including the rules for their properties and the conditions for the equivalence of various definitions. Finally, we proved the standard approaches to the Mittag-Leffler-Hyers-Ulam problem of the linear and nonlinear fractional differential equations with Prabhakar derivatives using a fractional Fourier transform.

Acknowledgment

The authors would like to thank the reviewers for their careful reading and valuable comments that helped in correcting and improving the paper.

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Received 19 February 2022
Accepted 26 April 2022