

## Generalized Hölder Estimates via Generalized Morrey Norms for Kolmogorov Operators

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**Abstract.** We obtain generalized Hölder estimates for Kolmogorov operators on  $\mathbb{R}^3$  by establishing several estimates for singular integrals in generalized Morrey spaces.

**Key Words and Phrases:** Kolmogorov operator, homogeneous type space, singular integral operators, generalized Morrey space, generalized Hölder estimate.

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### 1. Introduction and main results

The Kolmogorov equation was first introduced by Kolmogorov in 1934 to study the time evolution of the density of a Brownian test particle in the phase space. It is a linear strongly degenerate second order PDE whose diffusion part is governed by the Laplace operator in a subset of the variables (velocity variables) coupled with a transport term that contains the directions of missing ellipticity (position variables). Such a drift term makes the equation non-symmetric, but at the same time it is responsible for the hypoelliptic properties of the operator.

Let us consider a Kolmogorov operator in  $\mathbb{R}^3$ :

$$\mathcal{L} = \partial_{x_1 x_1}^2 + x_1 \partial_{x_2} - \partial_t. \quad (1)$$

Kolmogorov in [20] presented an explicit fundamental solution, smooth outside the pole, for the ultraparabolic operator  $\mathcal{L}$ , which, despite its degeneracy, possesses a fundamental solution  $\Gamma$  smooth outside the pole, this fact implying the hypoellipticity of  $\mathcal{L}$ . Actually,

$$\mathcal{L}((x_1, x_2, t), (y_1, y_2, \tau))$$

$$= \begin{cases} \frac{\sqrt{3}}{2\pi(t-\tau)^2} \exp\left(-\frac{x_1^2+x_1y_1+y_1^2}{t-\tau} - \frac{3(x_1+y_1)(x_2-y_2)}{(t-\tau)^2} - \frac{3(x_2-y_2)^2}{(t-\tau)^3}\right) & \text{for } t > \tau, \\ 0 & \text{for } t \leq \tau. \end{cases}$$

This phenomenon is well understood in the framework of the theory of Hörmander operators; actually, this operator can be written as  $\mathcal{L}u = X_1^2u + X_0u$  with

$$X_1 = \partial_{x_1}, \quad X_0 = -(x\partial_{x_2} + \partial_t),$$

and since  $[X_1, X_0] = -\partial_t$ , we see that  $X_1, X_0, [X_1, X_0]$  span  $\mathbb{R}^3$  at every point of the space, hence Hörmander’s condition is satisfied. This operator is explicitly quoted as a motivating example in the introduction of Hörmander’s paper [19] and, as was shown, is part of a large class of operators of Hörmander type which represent interesting physical models.

It is known that  $\mathcal{L}$  is a degenerate operator which appears in many research fields. For instance, the Kolmogorov equation

$$\partial_{x_1x_1}^2u + x_1\partial_{x_2}u - \partial_tu = 0, \quad (x_1, x_2, t) \in \mathbb{R}^3 \tag{2}$$

occurs in the financial problem (see [3, 12]), in the kinetic theory (see [8, 22]) as well as in the visual perception problem (see [26]).

The second order part in (2) is strongly degenerate due to the presence in it of the only term  $\partial_{x_1x_1}^2$ . However, Kolmogorov constructed in 1934 an explicit fundamental solution of (2) which is a  $C^\infty$  function outside the diagonal [24]. This implies that (2) is hypoelliptic, i.e. every distributional solution to (2) in an open subset  $\Omega$  of  $\mathbb{R}^3$ , actually is a  $C^\infty(\Omega)$  function.

We know that  $\mathcal{L}$  is a class of Kolmogorov-Fokker-Planck ultraparabolic operators. Due to its importance in physics and in mathematical finance, it has been extensively studied (see [5, 6, 13, 15, 21, 29, 30]). The authors in [13, 21, 29, 30] proved an invariant Harnack inequality for the non-negative solutions of the equation  $\mathcal{L}u = 0$ . The local  $L^p$  estimates have been studied in [5] and [6]. Based on the theory of singular integral, Polidoro and Ragusa in [31] obtained Morrey-type imbedding results and gave a local Holder continuity of the solution. In this paper, we obtain generalized Hölder estimates for Kolmogorov operators  $\mathcal{L}$  on  $\mathbb{R}^3$ .

Morrey spaces and their properties play an important role in the study of local behavior of solutions to elliptic partial differential equations, refer to [25, 28]. In [1, 4, 9], the authors showed the boundedness in Morrey spaces for some important operators in harmonic analysis such as Hardy-Littlewood operators, Calderón-Zygmund singular integral operators and fractional integral operators. Moreover, various Morrey spaces are defined in the process of study. In [16, 24, 27], the

authors introduced and studied the boundedness of the classical operators in generalized Morrey spaces  $M^{p,\varphi}(\mathbb{R}^n)$  (see, also [2, 17, 18, 32]), etc.

We find it convenient to define the generalized Morrey spaces in the form as follows.

**Definition 1.** (*Generalized Morrey space*). Let  $1 \leq p < \infty$  and  $\varphi(x, r)$  be a positive measurable function on  $\mathbb{R}^3 \times (0, \infty)$ . The generalized Morrey space  $M^{p,\varphi}(\mathbb{R}^3)$  is defined as a set of all functions  $f \in L^p_{\text{loc}}(\mathbb{R}^3)$  equipped with the finite norm

$$\|f\|_{M^{p,\varphi}(\mathbb{R}^3)} = \sup_{x \in \mathbb{R}^3, r > 0} \frac{r^{-\frac{6}{p}}}{\varphi(x, r)} \|f\|_{L^p(B(x,r))}.$$

Also, the weak generalized Morrey space  $WM^{p,\varphi}(\mathbb{R}^3)$  is defined as a set of all functions  $f \in L^p_{\text{loc}}(\mathbb{R}^3)$  equipped with the finite norm

$$\|f\|_{WM^{p,\varphi}(\mathbb{R}^3)} = \sup_{x \in \mathbb{R}^3, r > 0} \frac{r^{-\frac{6}{p}}}{\varphi(x, r)} \|f\|_{WL^p(B(x,r))}.$$

**Remark 1.** (1) If  $\varphi(x, r) = r^{\frac{\lambda-4}{p}}$  with  $0 < \lambda < 4$ , then  $M^{p,\varphi}(\mathbb{R}^3) = L^{p,\lambda}(\mathbb{R}^3)$  is the classical Morrey space and  $WM^{p,\varphi}(\mathbb{R}^3) = WL^{p,\lambda}(\mathbb{R}^3)$  is the weak Morrey space.

(2) If  $\varphi(x, r) \equiv r^{-\frac{6}{p}}$ , then  $M^{p,\varphi}(\mathbb{R}^3) = L^p(\mathbb{R}^3)$  is the Lebesgue space and  $WM^{p,\varphi}(\mathbb{R}^3) = WL^p(\mathbb{R}^3)$  is the weak Lebesgue space.

**Lemma 1.** [14] Let  $\varphi(x, r)$  be a positive measurable function on  $\mathbb{R}^3 \times (0, \infty)$ .

(i) If

$$\sup_{t < r < \infty} \frac{r^{-\frac{6}{p}}}{\varphi(x, r)} = \infty \quad \text{for some } t > 0 \quad \text{and for all } x \in \mathbb{R}^3,$$

then  $M^{p,\varphi}(\mathbb{R}^3) = \Theta$ .

(ii) If

$$\sup_{0 < r < \tau} \varphi(x, r)^{-1} = \infty \quad \text{for some } \tau > 0 \quad \text{and for all } x \in \mathbb{R}^3,$$

then  $M^{p,\varphi}(\mathbb{R}^3) = \Theta$ .

**Remark 2.** [14] We denote by  $\Omega_p$  the sets of all positive measurable functions  $\varphi$  on  $\mathbb{R}^3 \times (0, \infty)$  such that for all  $r > 0$ ,

$$\sup_{x \in \mathbb{R}^3} \left\| \frac{r^{-\frac{6}{p}}}{\varphi(x, r)} \right\|_{L^\infty(t, \infty)} < \infty, \quad \text{and} \quad \sup_{x \in \mathbb{R}^3} \left\| \varphi(x, r)^{-1} \right\|_{L^\infty(0, t)} < \infty,$$

respectively. In what follows, keeping in mind Lemma 1, we always assume that  $\varphi \in \Omega_p$ .

Define

$$[u]_{C^\omega(\mathbb{R}^3)} = \sup_{x, z \in \mathbb{R}^3, x \neq z} \frac{|u(x) - u(z)|}{\omega(\|x^{-1} \circ z\|)},$$

and set  $C^{0,\omega}(\mathbb{R}^3)$  for the space with the all functions  $u : \mathbb{R}^3 \rightarrow \mathbb{R}$  with the finite norm

$$\|u\|_{C^\omega(\mathbb{R}^3)} = \|u\|_{L^\infty(\mathbb{R}^3)} + [u]_{C^\omega(\mathbb{R}^3)}.$$

In the case  $\omega(t) = t^\alpha$ ,  $0 < \alpha \leq 1$ , we get the Hölder spaces  $C^\alpha(\mathbb{R}^3)$ .

The main results in this paper are as follows.

**Theorem 1.** *Let  $1 < p < \infty$  and  $\varphi = \varphi(x, r) \in \Omega_p$  satisfy the condition*

$$\int_0^1 \varphi(x, r) r \, dr + \int_1^\infty \varphi(x, r) \, dr < \infty.$$

*Then there exists a positive constant  $C$ , depending only on  $p$ ,  $\varphi$  and the operator  $\mathcal{L}$ , such that for every  $u \in C_0^\infty(\mathbb{R}^3)$ ,*

$$\begin{aligned} |u(x) - u(z)| &\leq C \|\mathcal{L}u\|_{M^{p,\varphi}(\mathbb{R}^3)} \\ &\times \left( \int_0^{\|x^{-1} \circ z\|} \varphi(x, r) r \, dr + \|x^{-1} \circ z\| \int_{\|x^{-1} \circ z\|}^\infty \varphi(x, r) \, dr \right) \end{aligned}$$

*for every  $x, z \in \mathbb{R}^3$ ,  $x \neq z$ , where  $\circ$  is the group law given in Section 2.*

*Let  $1 < p < \infty$  and  $\varphi = \varphi(x, r) \in \Omega_p$  satisfy the condition*

$$\int_0^1 \varphi(x, r) \, dr + \int_1^\infty \varphi(x, r) \frac{dr}{r} < \infty.$$

*Then there exists a positive constant  $C$ , depending only on  $p$ ,  $\varphi$  and the operator  $\mathcal{L}$ , such that for every  $u \in C_0^\infty(\mathbb{R}^3)$ ,*

$$\begin{aligned} |\partial_{x_1} u(x) - \partial_{x_1} u(z)| &\leq C \|\mathcal{L}u\|_{M^{p,\varphi}(\mathbb{R}^3)} \\ &\times \left( \int_0^{\|x^{-1} \circ z\|} \varphi(x, r) \, dr + \|x^{-1} \circ z\| \int_{\|x^{-1} \circ z\|}^\infty \varphi(x, r) \frac{dr}{r} \right) \end{aligned}$$

*for every  $x, y \in \mathbb{R}^3$ ,  $x \neq z$ .*

**Corollary 1.** Let  $1 < p < \infty$  and  $\varphi = \varphi(x, r) \in \Omega_p$  satisfy the condition

$$\int_0^\delta \varphi(x, r) r dr + \delta \int_\delta^\infty \varphi(x, r) dr \lesssim \varphi(x, \delta) \delta^2$$

for all  $x$  and  $\delta > 0$ . Then there exists a positive constant  $C$ , depending only on  $p$ ,  $\varphi$  and the operator  $\mathcal{L}$ , such that for every  $u \in C_0^\infty(\mathbb{R}^3)$ ,

$$|u(x) - u(z)| \leq C \|\mathcal{L}u\|_{M^{p,\varphi}(\mathbb{R}^3)} \varphi(x, \|x^{-1} \circ z\|) \|x^{-1} \circ z\|^2$$

for every  $x, z \in \mathbb{R}^3$ ,  $x \neq z$ , where  $\circ$  is the group law given in Section 2. Moreover,

$$\|u\|_{C^{\varphi(\cdot, r) r^2}(\mathbb{R}^3)} \lesssim \|\mathcal{L}u\|_{M^{p,\varphi}(\mathbb{R}^3)}.$$

Let  $1 < p < \infty$  and  $\varphi = \varphi(x, r) \in \Omega_p$  satisfy the condition

$$\int_0^\delta \varphi(x, r) dr + \delta \int_\delta^\infty \varphi(x, r) \frac{dr}{r} \lesssim \varphi(x, \delta) \delta$$

for all  $x$  and  $\delta > 0$ . Then there exists a positive constant  $C$ , depending only on  $p$ ,  $\varphi$  and the operator  $\mathcal{L}$ , such that for every  $u \in C_0^\infty(\mathbb{R}^3)$ ,

$$|\partial_{x_j} u(x) - \partial_{x_j} u(z)| \leq C \|\mathcal{L}u\|_{M^{p,\varphi}(\mathbb{R}^{n+1})} \varphi(x, \|x^{-1} \circ z\|) \|x^{-1} \circ z\|$$

for every  $x, z \in \mathbb{R}^3$ ,  $x \neq z$ . Moreover,

$$\|\partial_{x_1} u\|_{C^{\varphi(\cdot, r) r}(\mathbb{R}^3)} \lesssim \|\mathcal{L}u\|_{M^{p,\varphi}(\mathbb{R}^3)}.$$

Note that for  $\varphi(x, r) = |B(x, r)|^{\frac{\lambda-1}{p}}$ , from Theorem 1 we get the following result proven in [10].

**Corollary 2.** [10, Theorem 1.2] If  $2p + \lambda > 6$ ,  $p + \lambda < 6$  and  $\theta = \frac{2p+\lambda-6}{p}$ , then there exists a positive constant  $C$ , depending only on  $p$ ,  $\lambda$  and the operator  $\mathcal{L}$ , such that for every  $u \in C_0^\infty(\mathbb{R}^3)$ ,

$$|u(x) - u(z)| \leq C \|\mathcal{L}u\|_{L^{p,\lambda}(\mathbb{R}^3)} \|x^{-1} \circ x\|^\theta$$

for every  $x, z \in \mathbb{R}^3$ ,  $z \neq w$ , where  $\circ$  is the group law given in Section 2. Moreover,

$$\|u\|_{C^\theta(\mathbb{R}^3)} \lesssim \|\mathcal{L}u\|_{M^{p,\lambda}(\mathbb{R}^3)}.$$

If  $p + \lambda > 6$  and  $\delta = \frac{p+\lambda-6}{p}$ , then there exists a positive constant  $C$ , depending only on  $p$ ,  $\lambda$  and the operator  $\mathcal{L}$ , such that for every  $u \in C_0^\infty(\mathbb{R}^3)$ ,

$$|\partial_{x_1} u(x) - \partial_{x_1} u(z)| \leq C \|\mathcal{L}u\|_{L^{p,\lambda}(\mathbb{R}^3)} \|x^{-1} \circ z\|^\delta$$

for every  $x, z \in \mathbb{R}^3$ ,  $x \neq z$ . Moreover,

$$\|\partial_{x_1} u\|_{C^\delta(\mathbb{R}^3)} \lesssim \|\mathcal{L}u\|_{M^{p,\lambda}(\mathbb{R}^3)}.$$

The paper is organized as follows. In Section 2, we introduce some preliminary and known results which will be used later. The proof of Theorem 1 is given in Section 3.

### 2. Preliminaries

It is proved in [21] that the operator  $\mathcal{L}$  is left-invariant with respect to the Lie group  $\mathcal{K} = (\mathbb{R}^3, \circ)$ , whose underlying manifold is  $\mathbb{R}^3$ , endowed with the composition law

$$(x_1, x_2, t) \circ (x_1, x_2, \tau) = (x_1 + x_2, x_2 + y_2 - tx_1, t + \tau).$$

Note that

$$(x_1, x_2, t)^{-1} = (-x_1, -x_2 - tx_1, -t).$$

The left translation by  $y = (y_1, y_2, \tau)$  given by

$$(x_1, x_2, t) \rightarrow (y_1, y_2, \tau) \circ (x_1, x_2, t),$$

is an invariant translation to the operator  $\mathcal{L}$  given by

$$\delta_\lambda = \text{diag}(t, t^3, t^2),$$

where  $t$  is a positive parameter, and the homogeneous dimension of  $(\mathbb{R}^3, \circ)$  with respect to the dilation  $\delta_\lambda$  is 6.

**Remark 3.** *There is a natural homogeneous norm in  $\mathbb{R}^3$ , induced by dilation  $D(\lambda)$ :  $\|x\| \equiv \|(x_1, x_2, t)\| = |x_1| + |x_2|^{1/3} + |t|^{1/2}$ . Clearly, we have  $\|\delta_\lambda z\| = \lambda \|z\|$ ,  $\lambda > 0$ ,  $z \in \mathbb{R}^3$ .*

For every  $x, y \in \mathbb{R}^3$ , define a quasidistance by  $d(x, y) = \|y^{-1} \circ x\|$ . The ball with respect to  $d$  is denoted by

$$B(x, r) = B_r(x) = \{w \in \mathbb{R}^3 : d(x, y) < r\}. \tag{3}$$

Since  $B(0, r) = \delta_r B(0, 1)$  and  $\det(\delta_\lambda) = \lambda^6$ , we also have

$$|B_r(0)| = r^6 |B_1(0)|,$$

where  $|B_1(0)| = w_2$  is the Lebesgue measure of the Euclidean unit ball of  $\mathbb{R}^3$ . This implies that the Lebesgue measure  $dx$  is a doubling measure with respect to  $d$ , since

$$|B(x, 2r)| = 2^6 |B(x, r)|, \quad z \in \mathbb{R}^3, \quad r > 0.$$

Therefore, the space  $(\mathbb{R}^3, dx, d)$  is a space of homogenous type. Recall that if  $f$  and  $g$  are functions on  $\mathbb{R}^3$ , their convolution  $f * g$  is defined by

$$f * g(x) = \int_{\mathbb{R}^3} f(x \circ y^{-1})g(y)dy = \int_{\mathbb{R}^3} g(y^{-1} \circ x)f(y)dy.$$

For the operator  $\mathcal{L}$ , the fundamental solution  $\Gamma(\cdot, y)$  with pole in  $y = (y_1, y_2, \tau) \in \mathbb{R}^3$  is smooth except on diagonal of  $\mathbb{R}^3 \times \mathbb{R}^3$ . It has the following form at  $y = (0, 0, 0)$ :

$$\Gamma(x) = \Gamma(x, 0) = \begin{cases} \frac{\sqrt{3}}{2\pi t^2} \exp\left(-\frac{x_1^2}{t} - \frac{3x_1x_2}{t^2} - \frac{3x_2^2}{t^3}\right) & \text{for } t > 0, \\ 0 & \text{for } t \leq 0. \end{cases}$$

And

$$\Gamma(x, y) = \begin{cases} \frac{\sqrt{3}}{2\pi(t-\tau)^2} \exp\left(-\frac{x_1^2+x_1y_1+y_1^2}{t-\tau} - \frac{3(x_1+x_2)(x_2-y_2)}{(t-\tau)^2} - \frac{3(x_2-y_2)^2}{(t-\tau)^3}\right) & \text{for } t > \tau, \\ 0 & \text{for } t \leq \tau. \end{cases}$$

Moreover,  $\Gamma \in C^\infty(\mathbb{R}^3 \setminus \{0\})$ .

The authors in [11] and [33] proved a representation formula:

$$u(x) = -(\mathcal{L}u * \Gamma)(x) = - \int_{\mathbb{R}^3} \Gamma(y^{-1} \circ x)\mathcal{L}u(y)dy. \tag{4}$$

The following formula was given by Bramanti in [7]:

$$\partial_{x_1x_1}^2 u(x) = -P.V. (\mathcal{L}u * \partial_{x_1x_1}^2 \Gamma)(x) + c_{11}\mathcal{L}u(x) \tag{5}$$

for every  $u \in C_0^\infty(\mathbb{R}^3)$  and some constant  $c_{11}$ . The principal value in (5) is understood as

$$P.V. (\mathcal{L}u * \partial_{x_1x_1}^2 \Gamma)(x) = \lim_{\varepsilon \rightarrow 0} \int_{\mathbb{R}^3 \setminus B(z, \varepsilon)} (\partial_{x_1x_1}^2 \Gamma)(y^{-1} \circ x)\mathcal{L}u(Y)dy.$$

Set

$$\Gamma_1(x) = \partial_{x_1}\Gamma(x), \quad \Gamma_{11}(x) = \partial_{x_1}\partial_{x_1}\Gamma(x).$$

We also observe that  $\Gamma(x)$  is homogeneous of degree  $-4$  with respect to the group  $(\delta_\lambda)_{\lambda>0}$ , and  $\Gamma_1(x)$  is homogeneous of degree  $-5$ . Recall that  $\Gamma_{11}(\cdot)$  has the following properties.

**Lemma 2.** ([6]). *One has*

- (a)  $\Gamma_{11}(\cdot) \in C^\infty(\mathbb{R}^3 \setminus \{0\})$ ;
- (b)  $\Gamma_{11}(\cdot)$  is homogeneous of degree  $-6$ ;
- (c) for every  $R > r > 0$ ,

$$\int_{r < \|x\| < R} \Gamma_{11}(x)dx = \int_{\|z\|=1} \Gamma_{11}(x)d\sigma(x) = 0.$$

### 3. Generalized Hölder continuity

In this section, by demonstrating generalized Hölder estimates for two integral operators, we prove Theorem 1.

**Lemma 3.** [23]. *Let  $K \in C^1(\mathbb{R}^3 \setminus \{0\})$  be a homogeneous function of degree  $b < 1$  with respect to the group  $(\delta_\lambda)_{\lambda>0}$ . There exist two constants  $c > 0$  and  $M > 1$  such that if  $\|x\| > M\|x^{-1} \circ y\|$ , then*

$$|K(y) - K(x)| \leq c\|x^{-1} \circ y\| \cdot \|x\|^{b-1}.$$

**Lemma 4.** [23] *For every  $x, y, z \in \mathbb{R}^3$ , the following assertions hold:*

(1) *there exists a constant  $c > 0$  such that*

$$\Gamma(x^{-1} \circ y) \leq \frac{c}{\|x^{-1} \circ y\|^4}, \quad \Gamma_i(x^{-1} \circ y) \leq \frac{c}{\|x^{-1} \circ y\|^5}.$$

(2) *there exist two constants  $c > 0$  and  $M > 1$  such that if  $\|x^{-1} \circ z\| \geq M\|x^{-1} \circ y\|$ , then*

$$|\Gamma(x^{-1} \circ z) - \Gamma(x^{-1} \circ y)| \leq \frac{c\|z^{-1} \circ y\|}{\|x^{-1} \circ z\|^5},$$

$$|\Gamma_i(x^{-1} \circ z) - \Gamma_i(x^{-1} \circ y)| \leq \frac{c\|z^{-1} \circ y\|}{\|x^{-1} \circ z\|^6}.$$

**Lemma 5.** *Let  $p \in (1, \infty)$  and  $\lambda \in [0, 6)$ . With fixed  $z \in \mathbb{R}^3$ ,  $\alpha \in [0, 6)$ ,  $\beta \in (0, 6)$  and  $\sigma > 0$ , for every  $g \in M^{p,\varphi}(\mathbb{R}^3)$ , we set*

$$T'_\alpha g(x) = \int_{\|y^{-1} \circ x\| \geq \sigma \|z^{-1} \circ x\|} \frac{g(y)}{\|y^{-1} \circ x\|^{6-\alpha}} dy$$

and

$$T''_\beta g(x) = \int_{\|y^{-1} \circ x\| < \sigma \|z^{-1} \circ x\|} \frac{g(y)}{\|y^{-1} \circ x\|^{6-\beta}} dy.$$

*If  $\int_1^\infty \varphi(x, r) r^{\alpha-1} dr < \infty$ , then there exists  $c = c(p, \varphi, \alpha, \sigma) > 0$  such that*

$$|T'_\alpha g(x)| \leq c \|g\|_{M^{p,\varphi}(\mathbb{R}^3)} \int_{\|z^{-1} \circ x\|}^\infty \varphi(x, r) r^{\alpha-1} dr. \tag{6}$$

*Moreover, if  $\int_0^1 \varphi(x, r) r^{\beta-1} dr < \infty$ , then there exists  $c = c(p, \varphi, \beta, \sigma) > 0$  such that*

$$|T''_\beta g(x)| \leq c \|g\|_{M^{p,\varphi}(\mathbb{R}^3)} \int_0^{\|z^{-1} \circ x\|} \varphi(x, r) r^{\beta-1} dt. \tag{7}$$



*Proof.* Observing that

$$\begin{aligned}
|T'_\alpha g(x)| &\leq \sum_{k=1}^{\infty} \int_{2^{k-1}\sigma\|z^{-1}\circ x\| \leq \|y^{-1}\circ x\| < 2^k\sigma\|z^{-1}\circ x\|} \frac{|g(y)|}{\|y^{-1}\circ x\|^{6-\alpha}} dy \\
&\leq \sum_{k=1}^{\infty} \left(\frac{2}{2^k\sigma\|z^{-1}\circ x\|}\right)^{6-\alpha} \int_{B_{2^k c_1 \sigma\|z^{-1}\circ x\|}(x)} |g(y)| dy \\
&\leq \sum_{k=1}^{\infty} \left(\frac{2}{2^k\sigma\|z^{-1}\circ x\|}\right)^{6-\alpha} \|g\|_{L^p(B_{2^k c_1 \sigma\|z^{-1}\circ x\|}(x))} |B_{2^k c_1 \sigma\|z^{-1}\circ x\|}(x)|^{\frac{1}{p'}} \\
&\leq \sum_{k=1}^{\infty} \left(\frac{2}{2^k\sigma\|z^{-1}\circ x\|}\right)^{\frac{6}{p}-\alpha} \|g\|_{L^p(B_{2^k c_1 \sigma\|z^{-1}\circ x\|}(x))} \lesssim \|g\|_{M^{p,\varphi}(\mathbb{R}^3)} \\
&\times \sum_{k=1}^{\infty} \left(\frac{2}{2^k\sigma\|z^{-1}\circ x\|}\right)^{\frac{6}{p}-\alpha} (2^k\sigma\|z^{-1}\circ x\|)^{\frac{6}{p}} \varphi(x, 2^k c_1 \sigma\|z^{-1}\circ x\|) \\
&\lesssim \|g\|_{M^{p,\varphi}(\mathbb{R}^3)} \sum_{k=1}^{\infty} \left(2^k\sigma\|z^{-1}\circ x\|\right)^\alpha \varphi(x, 2^k\sigma\|z^{-1}\circ x\|) \\
&\lesssim \|g\|_{M^{p,\varphi}(\mathbb{R}^3)} \int_{\|z^{-1}\circ x\|}^{\infty} \varphi(x, r) r^{\alpha-1} dr,
\end{aligned}$$

we see that (6) is true, since the above series is convergent.

Similarly, by integrating over the set

$$\{y \in \mathbb{R}^3 : 2^{-k}\sigma\|z^{-1}\circ x\| \leq \|y^{-1}\circ x\| < 2^{1-k}\sigma\|z^{-1}\circ x\|\},$$

we get

$$\begin{aligned}
|T''_\beta g(x)| &\leq \sum_{k=1}^{\infty} \int_{2^{-k}\sigma\|z^{-1}\circ x\| \leq \|y^{-1}\circ x\| < 2^{1-k}\sigma\|z^{-1}\circ x\|} \frac{|g(y)|}{\|y^{-1}\circ x\|^{6-\beta}} dy \\
&\leq \sum_{k=1}^{\infty} \left(\frac{2}{2^{1-k}\sigma\|z^{-1}\circ x\|}\right)^{6-\beta} \int_{B_{2^{1-k} c_1 \sigma\|z^{-1}\circ x\|}(x)} |g(y)| dy \\
&\leq \sum_{k=1}^{\infty} \left(\frac{2}{2^{1-k}\sigma\|z^{-1}\circ x\|}\right)^{6-\beta} \|g\|_{L^p(B_{2^{1-k} c_1 \sigma\|z^{-1}\circ x\|}(x))} |B_{2^{1-k} c_1 \sigma\|z^{-1}\circ x\|}(x)|^{\frac{1}{p'}} \\
&\leq \sum_{k=1}^{\infty} \left(\frac{2}{2^{1-k}\sigma\|z^{-1}\circ x\|}\right)^{\frac{6}{p}-\beta} \|g\|_{L^p(B_{2^{1-k} c_1 \sigma\|z^{-1}\circ x\|}(x))} \lesssim \|g\|_{M^{p,\varphi}(\mathbb{R}^3)} \\
&\times \sum_{k=1}^{\infty} \left(\frac{1}{2^{-k}\sigma\|z^{-1}\circ x\|}\right)^{\frac{6}{p}-\beta} (2^{-k}\sigma\|z^{-1}\circ x\|)^{\frac{6}{p}} \varphi(x, 2^{-k}\sigma\|z^{-1}\circ x\|)
\end{aligned}$$

$$\begin{aligned} &\lesssim \|g\|_{M^{p,\varphi}(\mathbb{R}^3)} \sum_{k=1}^{\infty} \left(2^{-k} \sigma \|z^{-1} \circ x\|\right)^\beta \varphi(x, 2^{-k} \sigma \|z^{-1} \circ z\|) \\ &\lesssim \|g\|_{M^{p,\varphi}(\mathbb{R}^3)} \int_0^{\|z^{-1} \circ x\|} \varphi(x, r) r^{\beta-1} dr. \end{aligned}$$

As the above series is convergent, (7) is proved. ◀

*Proof of Theorem 1.* For  $u \in C_0^\infty(\mathbb{R}^3)$ , by Lemmas 4 and 5, there exist  $M, c > 0$  such that

$$\begin{aligned} |u(x) - u(z)| &\leq \int_{\mathbb{R}^3} |\Gamma(y^{-1} \circ x) - \Gamma(y^{-1} \circ z)| |\mathcal{L}(y)| dy \\ &\lesssim \int_{\|y^{-1} \circ z\| \geq M \|x^{-1} \circ z\|} \frac{\|x^{-1} \circ z\|}{\|y^{-1} \circ x\|^5} |\mathcal{L}u(y)| dy \\ &\quad + \int_{\|y^{-1} \circ x\| < M \|x^{-1} \circ z\|} \frac{1}{\|y^{-1} \circ x\|^4} |\mathcal{L}u(y)| dy \\ &\quad + \int_{\|y^{-1} \circ x\| < M \|x^{-1} \circ z\|} \frac{1}{\|y^{-1} \circ z\|^4} |\mathcal{L}u(y)| dy \\ &\equiv I_1 + I_2 + I_3. \end{aligned}$$

By applying Lemma 5 and choosing  $\alpha = 1$  and  $\sigma = M/c_1$ , we obtain the existence of a positive constant  $c$  such that

$$|I_1| \lesssim \|\mathcal{L}u\|_{M^{p,\varphi}(\mathbb{R}^3)} \|x^{-1} \circ z\| \int_{\|x^{-1} \circ z\|}^{\infty} \varphi(x, r) dr. \tag{8}$$

Choosing  $\beta = 2$  and  $\sigma = Mc_1$  in Lemma 5, we obtain the existence of a positive constant  $c$  such that

$$|I_2| \lesssim \|\mathcal{L}u\|_{M^{p,\varphi}(\mathbb{R}^3)} \int_0^{\|x^{-1} \circ z\|} \varphi(x, r) r dr. \tag{9}$$

Choosing  $\beta = 2$  and  $\sigma = c_2(1 + M)$  in Lemma 5, we obtain the existence of a positive constant  $c$  such that

$$|I_3| \lesssim \|\mathcal{L}u\|_{M^{p,\varphi}(\mathbb{R}^3)} \int_0^{\|x^{-1} \circ z\|} \varphi(x, r) r dr. \tag{10}$$

Hence, by (8), (9) and (10), it is easy to obtain

$$|u(x) - u(z)| \leq C \|\mathcal{L}u\|_{M^{p,\varphi}(\mathbb{R}^3)}$$

$$\times \left( \int_0^{\|x^{-1} \circ z\|} \varphi(x, r) r \, dr + \|x^{-1} \circ z\| \int_{\|x^{-1} \circ z\|}^{\infty} \varphi(x, r) \, dr \right),$$

where  $C$  is a positive constant,  $x, z \in \mathbb{R}^3$ ,  $x \neq z$ .

By (4), we write

$$\partial_{x_1} u(x) = - \int_{\mathbb{R}^3} \Gamma_1(y^{-1} \circ x) \mathcal{L}u(y) \, dy$$

for every  $x \in \mathbb{R}^3$ . Analogously, by Lemmas 4 and 5, we obtain the existence of  $M, c > 0$  such that

$$\begin{aligned} |\partial_{x_1} u(x) - \partial_{x_1} u(z)| &\leq \int_{\mathbb{R}^3} |\Gamma_1(y^{-1} \circ x) - \Gamma_1(y^{-1} \circ z)| |\mathcal{L}u(y)| \, dy \\ &\leq \int_{\|y^{-1} \circ x\| \geq M \|x^{-1} \circ z\|} \frac{c \|x^{-1} \circ z\|}{\|y^{-1} \circ x\|^6} |\mathcal{L}u(y)| \, dy \\ &\quad + \int_{\|y^{-1} \circ x\| < M \|x^{-1} \circ z\|} \frac{c}{\|y^{-1} \circ x\|^5} |\mathcal{L}u(y)| \, dy \\ &\quad + \int_{\|y^{-1} \circ x\| < M \|x^{-1} \circ z\|} \frac{c}{\|y^{-1} \circ z\|^5} |\mathcal{L}u(y)| \, dy \\ &\equiv I'_1 + I'_2 + I'_3. \end{aligned}$$

By applying Lemma 5 and choosing  $\alpha = 0$  and  $\sigma = M/c_1$ , we obtain the existence of a positive constant  $c$  such that

$$|I'_1| \lesssim \|\mathcal{L}u\|_{M^p, \varphi(\mathbb{R}^3)} \|x^{-1} \circ z\| \int_{\|x^{-1} \circ z\|}^{\infty} \varphi(x, r) \frac{dr}{r}. \tag{11}$$

Choosing  $\beta = 1$  and  $\sigma = M c_1$  in Lemma 5, we obtain the existence of a positive constant  $c$  such that

$$|I'_2| \leq c \|\mathcal{L}u\|_{M^p, \varphi(\mathbb{R}^3)} \int_0^{\|x^{-1} \circ z\|} \varphi(x, r) \, dr. \tag{12}$$

Choosing  $\beta = 1$  and  $\sigma = c_2(1 + M)$  in Lemma 5, we obtain the existence of a positive constant  $c$  such that

$$|I'_3| \leq c \|\mathcal{L}u\|_{M^p, \varphi(\mathbb{R}^3)} \int_0^{\|x^{-1} \circ z\|} \varphi(x, r) \, dr. \tag{13}$$

Hence, by (11), (12) and (13), we derive

$$|\partial_{x_1} u(x) - \partial_{x_1} u(z)| \leq C \|\mathcal{L}u\|_{M^p, \varphi(\mathbb{R}^3)}$$

$$\times \left( \int_0^{\|x^{-1} \circ z\|} \varphi(x, r) \, dr + \|x^{-1} \circ z\| \int_{\|x^{-1} \circ z\|}^{\infty} \varphi(x, r) \frac{dr}{r} \right),$$

where  $C$  is a positive constant,  $x, z \in \mathbb{R}^3$ ,  $x \neq z$ . This completes the proof. ◀

*Proof of Corollary 2.* If we take  $\varphi(x, r) = |B(x, r)|^{\frac{\lambda-1}{p}}$  in Theorem 5, then we get

$$\int_{\|z^{-1} \circ x\|}^{\infty} \varphi(x, r) r^{\alpha-1} \, dr = \int_{\|z^{-1} \circ x\|}^{\infty} r^{\frac{\lambda-6}{p} + \alpha - 1} \, dr = \|z^{-1} \circ x\|^{\frac{\lambda-6}{p} + \alpha}$$

and

$$\begin{aligned} \int_1^{\infty} \varphi(x, r) r^{\alpha-1} \, dr &= \int_1^{\infty} r^{\frac{\lambda-6}{p} + \alpha - 1} \, dr < \infty \Leftrightarrow \frac{\lambda-6}{p} + \alpha > 0 \\ &\Leftrightarrow \lambda + p\alpha < 6. \end{aligned}$$

Also,

$$\int_0^{\|z^{-1} \circ x\|} \varphi(x, r) r^{\beta-1} \, dr = \int_0^{\|z^{-1} \circ x\|} r^{\frac{\lambda-6}{p} + \beta - 1} \, dr = \|z^{-1} \circ x\|^{\frac{\lambda-6}{p} + \beta}$$

and

$$\begin{aligned} \int_0^1 \varphi(x, r) r^{\beta-1} \, dr &= \int_0^1 r^{\frac{\lambda-6}{p} + \beta - 1} \, dr < \infty \Leftrightarrow \frac{\lambda-6}{p} + \beta > 0 \\ &\Leftrightarrow \lambda + p\beta > 6. \end{aligned}$$

This completes the proof. ◀

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